### CSI62Week 4

Kyle Dewey

#### Overview

- Reactive imperative programming refresher
- Rest of newCons
- What atomic is
- Implementation details

# Reactive Imperative Programming Refresher

### Basic Semantics

- Execute code in what newCons delimits
- Mark addresses used inside what newCons delimits as reactive
- When these are changed outside of the same newCons, trigger the delimited code (a.k.a, the constraint)

#### newCons Output: var a in a := 0; 10 newCons { output a // `a` is reactive }; while (a < 10) { a := a + 1 // trigger `output` }

#### Questions

- Is this enough detail to implement newCons?
- Is this enough detail to use newCons?

## Multiple Constraints #I

var a in a := 0; Output: newCons { output a }; newCons { 10 output a + 1 }; a := 10

## Cyclical Constraints

var a in a := 0; newCons { a := a + 1; output a }; a := 3

**Output:** 

## Multiple Constraints #2

var a in Output: a := 3; 3 newCons { 4 output a 6 }; 6 newCons { a := a + 1 }; a := 5

#### Nested Constraints

Output: var a, b in a := 4; <<newline>> b := ""; b newCons { 5 output a; b newCons { bb output b 5 }; t b := b + "b" tb }; tb a := 5; b := "t"

## newCons with Objects

• What does this output?

### The Point

- There are a lot of different edge cases
- As the language designer, these should all be accounted for

#### atomic Blocks

### Problem

- We need to update a variable multiple times during a loop
- The computation is not "done" until the last assignment
- We want to update only when the computation is done

## Example

Output: var a in 3 a := 0; 6 newCons { 9 output a 12 }; 24 while (a < 11) { a := a + 3 }; a := a + a // now `a` is ready

# Hacky Solution

- Add a flag isDone
  - Set to false beforehand
  - Set to true when a constraint is ready
  - In the constraint, only process if isDone
     is true

## **Better Solution**

- Let the language handle it
- Introduce a special atomic block
  - Constraints are only updated once we leave the atomic block
  - Instead of having multiple updates of the same constraint, only update the constraint once at the end

#### With atomic

```
var a in
                             Output:
a := 0;
newCons {
                               24
  output a
};
atomic {
  while (a < 11) {
    a := a + 3
  };
  a := a + a // now `a` is ready
}
```

Nesting atomic var a, b in newCons { Output: output b undef }; undef newCons { 3 output a 4 }; atomic { a := 2; atomic { b := 4 }; a := 3

# Implementation Details

## **Evaluation Modes**

- The interpreter can be in one of three modes:
  - Normal mode (normal execution)
  - Constraint mode
  - Atomic Mode
- See domains.scala

## Constraint Mode

- Whenever the body of a newCons block is executed
  - First entrance of newCons
  - When a reactive address is updated in normal mode or constraint mode
  - When we exit all atomic blocks
- Stores which constraint is currently being executed (useful for preventing recursive constraints)

## Atomic Mode

- Whenever we execute the body of an atomic block
  - No constraints are triggered in this mode
  - Store reactive addresses that were updated to trigger them once we leave atomic mode

#### Data Structures

#### • Dependencies

- Maps reactive addresses to sets of constraints
- See domains.scala
- constraintStack
- atomicStack

#### constraintStack

- For nested new constraints
- Records which constraint is currently active

#### atomicStack

- For nested atomic blocks
- Records which reactive addresses need constraint updates upon leaving the last atomic block

# Tips

- Never execute a constraint when you are in atomic mode
- Self-recursive constraints should never trigger themselves
- Reactive addresses can be both added and removed via newCons, depending on what gets used in the newCons' body
  - If a previously reactive address is not used when executing a constraint newCons, the address is no longer reactive